

UNIVERSITY OF SWAZILAND

FINAL EXAMINATIONS 2008/9

TITLE OF PAPER : DYNAMICS II

COURSE NUMBER : M 355

TIME ALLOWED : THREE (3) HOURS

INSTRUCTIONS : 1. THIS PAPER CONSISTS OF
SEVEN QUESTIONS.
2. ANSWER ANY FIVE QUESTIONS

THIS EXAMINATION PAPER SHOULD NOT BE OPENED UNTIL
PERMISSION HAS BEEN GRANTED BY THE INVIGILATOR.

QUESTION 1

(a) Prove that if the transformation equations are given by $r_\nu = r_\nu(q_1, q_2, \dots, q_n, t)$ then

$$(i) \quad \frac{\partial \dot{r}_\nu}{\partial \dot{q}_\alpha} = \frac{\partial r_\nu}{\partial q_\alpha} \quad (ii) \quad \frac{d}{dt} \left(\frac{\partial r_\nu}{\partial q_\alpha} \right) = \frac{\partial \dot{r}_\nu}{\partial q_\alpha}. \quad [8]$$

(b) Define the Poisson bracket of the two quantities F and G . [3]

(c) If $f = f(p_\alpha, q_\alpha, t)$ and H is the Hamiltonian, prove that

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + [H, f].$$

[4]

(d) For a certain dynamical system the kinetic and potential energy are given by

$$T = \frac{1}{2} ((1 + 2k)\dot{\theta}^2 + 2\dot{\theta}\dot{\phi} + \dot{\phi}^2)$$

$$V = \frac{n^2}{2} ((1 + k)\theta^2 + \phi^2)$$

where θ and ϕ are generalized coordinates and n, k are positive constants. Write down Lagrange's equations of motion and deduce that

$$(\ddot{\theta} - \ddot{\phi}) + n^2 \left(\frac{1+k}{k} \right) (\theta - \phi) = 0.$$

[10marks]

QUESTION 2

(a) A particle of mass m moves in one dimension such that it has the Lagrangian

$$L = \frac{m^2 \dot{x}^4}{12} + m\dot{x}^2 V(x) - V^2(x),$$

where V is some differentiable function of x . Show that the equation of motion reduces to

$$\left(m\ddot{x} + \frac{dV}{dx} \right) (m\dot{x}^2 + 2V(x)) = 0.$$

[10 marks]

(b) The kinetic and potential energy of a certain system are given by

$$T = \frac{1}{2}m(\dot{r}^2 + r^2\dot{\phi}^2 \sin^2 \alpha)$$

$$V = mgr \cos \alpha$$

where α is a constant. Use the Hamiltonian formulation to show that the angular momentum p_ϕ is conserved and is given by $p_\phi = mh \sin^2 \alpha$ where $h = r^2 \dot{\phi}$ is a known constant in the theory of forces. [10 marks]

QUESTION 3

(a) Use the Poisson bracket to show that the transformation

$$q = \sqrt{\frac{P}{\pi\omega}} \sin(2\pi Q) \quad , \quad p = \sqrt{\frac{\omega P}{\pi}} \cos(2\pi Q)$$

is canonical.

[6 marks]

(b) Consider the transformation given by

$$Q = q^\alpha e^{\beta p} \quad , \quad P = q^\alpha e^{-\beta p}$$

where α and β are constants. For which values of α and β is this transformation canonical?

[5 marks]

(c) Given that,

$$\begin{aligned} A_1 &= \frac{1}{4}(x^2 + p_x^2 - y^2 - p_y^2), & A_2 &= \frac{1}{2}(xy + p_x p_y) \\ A_3 &= \frac{1}{2}(x p_y - y p_x), & A_4 &= x^2 + y^2 + p_x^2 + p_y^2 \end{aligned}$$

where x and y are generalized coordinates, and p_x and p_y are the generalized momenta, associates with x and y respectively. Evaluate

(i) $[A_1, A_2]$ [3 marks]

(ii) $[A_3, A_4]$ [3 marks]

(iii) $[A_3, A_2]$ [3 marks]

QUESTION 4

(a) Prove that if F has no explicit dependence on y then

$$\frac{\partial F}{\partial y'} = \text{Constant}$$

[3 marks]

(b) Prove that if F has no explicit dependence on y' then

$$F = \text{Constant}$$

[2 marks]

(c) Show that the Euler-Lagrange equation for the functional

$$I = \int_a^b F(x, y, y', y'') dx \text{ is}$$

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) + \frac{d^2}{dx^2} \left(\frac{\partial F}{\partial y''} \right) = 0$$

[15 marks]

QUESTION 5

Use three methods you have studied to check if the following transformation is canonical. State clearly which method you use each time.

$$P = \frac{1}{2}(p^2 + q^2), \quad Q = \arctan\left(\frac{q}{p}\right) \quad [20 \text{ marks}]$$

(NB: do not use the poisson bracket)

QUESTION 6

(a) Find the extremals of the functional

$$\int_0^{\frac{\pi}{2}} (\dot{x}_1^2 + \dot{x}_2^2 + 2x_1x_2) dt$$

$$\text{when } x_1(0) = 0, \quad x_1\left(\frac{\pi}{2}\right) = 1, \quad x_2(0) = 0, \quad x_2\left(\frac{\pi}{2}\right) = 1 \quad [9 \text{ marks}]$$

(b) Consider a system with Hamiltonian

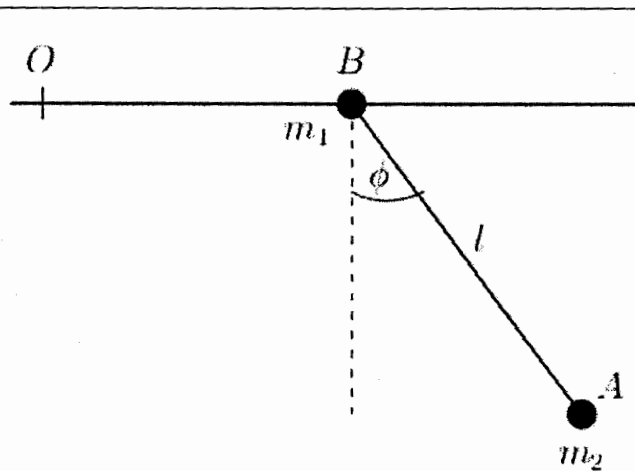
$$H = \frac{1}{2}(p_1^2 + q_1^2 + p_2^2 + q_2^2)$$

show that $M = p_1p_2 + q_1q_2$ and $L = p_1q_2 - q_1p_2$ are constants of motion by evaluating the poisson brackets $[M, H]$ and $[L, H]$. [8 marks]

(c) Is $M - L$ a constant of motion? [3 marks]

QUESTION 7

A simple pendulum of mass m_2 is attached to a mass m_1 which can move freely along the horizontal line, as shown in the Figure below. The system is in a uniform gravitational field (acceleration g).



Choosing the generalized coordinates to be x , the distance moved by m_1 from O , and ϕ , the inclination of BA to the vertical,

(a) Write down the transformation equation. [5]

(b) Derive the Lagrangian function of the system. [6]

(c) Prove that Lagrange's equation of motion corresponding to the generalized coordinate ϕ is

$$l\ddot{\phi} + \ddot{x} \cos \phi + g \sin \phi = 0$$

[6]

(d) Write down the Lagrange's equation of motion corresponding to x .

[3]