

# University of Swaziland

## Supplementary Examination, July 2018

### B.A.S.S. , B.Sc, B.Ed

Title of Paper : Dynamics II

Course Number : M355

Time Allowed : Three (3) Hours

#### Instructions

1. This paper consists of TWO sections.
  - a. **SECTION A (COMPULSORY): 40 MARKS**  
Answer ALL QUESTIONS.
  - b. **SECTION B: 60 MARKS**  
Answer ANY THREE questions.  
**Submit solutions to ONLY THREE questions in Section B.**
2. Each question in Section B is worth 20%.
3. Show all your working.
4. Non programmable calculators may be used (unless otherwise stated).
5. Special requirements: None.

THIS PAPER SHOULD NOT BE OPENED UNTIL PERMISSION HAS BEEN GIVEN BY THE INVIGILATOR.

## SECTION A: Answer All Questions

A1. (a) Define generalized coordinates, giving examples. [3]

(b) A particular mechanical system depending on two coordinates  $u$  and  $\nu$  has kinetic energy  $T = \nu^2 \dot{u}^2 + 2\dot{\nu}^2$ , and potential energy  $V = u^2 - \nu^2$ . Write down the Lagrangian for the system and deduce the system's equations of motion. [6]

A2. (a) Define the Hamiltonian function  $H$  in terms of the Lagrangian function,  $L$ . [3]

(b) Derive the Hamilton's equations when  $H$  does not depend on time  $t$ , explicitly. [6]

A3. Show that the following transformation of one degree of freedom is canonical

$$P = \frac{1}{2}(p^2 + q^2), \quad Q = \tan^{-1} \left( \frac{q}{p} \right).$$

[8]

A4. (a) Define a Poisson bracket between two physical quantities  $F(q_\alpha, p_\alpha, t)$  and  $G(q_\alpha, p_\alpha, t)$ . [3]

(b) Consider a system with Hamiltonian  $\frac{1}{2}(p_1^2 + q_1^2 + p_2^2 + q_2^2)$ . Show that  $M = p_1 p_2 + q_1 q_2$  is a constant of motion by evaluating the Poisson bracket  $[M, H]$ . [6]

A5. Find the curve  $y(x)$  that minimizes the functional

$$\int_0^{\frac{\pi}{2}} (y'^2 - y^2) dx, \quad y(0) = 0, \quad y\left(\frac{\pi}{2}\right) = 1.$$

[5]

## SECTION B: Answer Any THREE Questions

- B2.** (a) A double pendulum consists of two simple pendulums of lengths  $l_1$  and  $l_2$  and masses  $m_1$  and  $m_2$ , with the cord of one pendulum attached to the bob of another pendulum whose cord is fixed to a pivot, (see Figure 1). Determine the equations of motion for small angle oscillations using Lagrange's equations. [12]

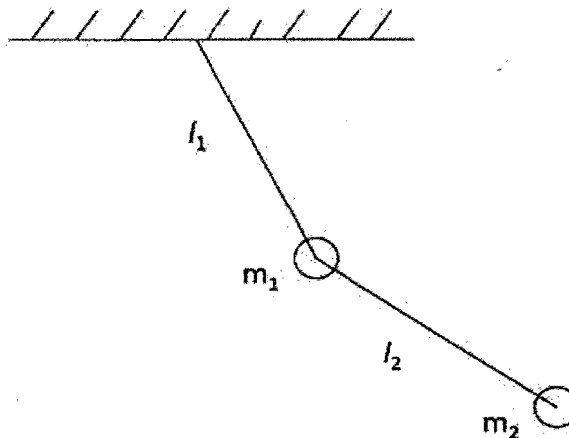


Figure 1: Double Pendulum

- (b) A particle moves in the  $xy$ -plane subject to the Lagrangian

$$\frac{1}{2}(\dot{x}^2 + \dot{y}^2) + \Omega(-\dot{x}y + \dot{y}x),$$

where  $\Omega$  is a constant. Find the Hamiltonian of the system and show that it is conserved. [8]

- B3.** Suppose that a system has a Hamiltonian defined by

$$\frac{1}{2m}(p_x^2 + m^2\omega^2x^2) + \frac{1}{2m}(p_y^2 + m^2\omega^2y^2).$$

- (a) Show, using Hamilton's equations, that the equations of motion can be written as

$$\ddot{x} + \omega^2x = 0, \quad \ddot{y} + \omega^2y = 0.$$

[10]

- (b) Evaluate the Poisson bracket  $[G, H]$  where

$$G = \frac{1}{2m\omega}(p_x p_y + m^2\omega^2xy), \quad H = \frac{1}{4m\omega}(p_x^2 - p_y^2 + m^2\omega^2(x^2 - y^2)).$$

[10]

- B4.** (a) Prove that for a system whose dynamic behavior defined is by the Hamiltonian  $H = H(q_\alpha, p_\alpha, t)$ , the equation of motion for a dynamic variable  $f(q_\alpha, p_\alpha, t)$  is

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + [f, H].$$

[4]

- (b) The Hamiltonian of a two-dimensional harmonic oscillator of unit mass is given by

$$H = \frac{1}{2}(p_1^2 + p_2^2) + \frac{1}{2}\omega(q_1^2 + q_2^2)$$

where  $\omega$  is a constant. Given that  $f = \omega q_1 \sin \omega t + \omega p_1 \cos \omega t$ , show that  $f$  is a constant of motion. [8]

- (c) For what values of the constant parameters  $\alpha$  and  $\beta$  is the transformation below canonical?

$$q = \beta P^\alpha \sin Q, \quad p = \beta P^\alpha \cos Q.$$

[8]

- B5.** (a) A system of two degrees of freedom is described by the Hamiltonian

$$H = q_1 p_1 - q_2 p_2 - a q_1^2 + b q_2^2,$$

where  $a$  and  $b$  are constants. Show that

$$F_1 = \frac{p_1 - a q_1}{q_2}, \quad \text{and} \quad F_2 = q_1 q_2,$$

are constants of motion. [10]

- (b) Find the curve  $y(x)$  that minimises the following functional

$$\int_0^1 (y' + (1+x)y'^2) dx, \quad y(0) = 0, \quad y(1) = \ln 2.$$

[10]

- B6.** (a) Show that if  $F$  has no explicit dependence on  $x$  (i.e.  $\partial F/\partial x = 0$ ) then  $F = F(y, y')$  and the Euler-Lagrange's equation simplifies to the Beltrami-identity which is defined by the equation

$$F - y' \frac{\partial F}{\partial y'} = C$$

where  $C$  is a constant.

[10]

- (b) Use the Beltrami identity to show that the extremum for the integral

$$I = \int_{x=0}^a \sqrt{\frac{1 + y'^2}{2y}} dx$$

is given by

$$y' = \sqrt{\frac{c - y}{y}}.$$

[10]

**END OF EXAMINATION**