

UNIVERSITY OF SWAZILAND

FACULTY OF SCIENCE

DEPARTMENT OF PHYSICS

MAIN EXAMINATION 2007/2008

**TITLE OF PAPER : MATHEMATICAL METHODS FOR
PHYSICISTS**

COURSE NUMBER : P272

TIME ALLOWED : THREE HOURS

**INSTRUCTIONS : ANSWER ANY FOUR OUT OF FIVE
QUESTIONS.
EACH QUESTION CARRIES 25 MARKS.**

**MARKS FOR DIFFERENT SECTIONS ARE
SHOWN IN THE RIGHT-HAND MARGIN.**

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GIVEN BY THE INVIGILATOR.**

P272 MATHEMATICAL METHODS FOR PHYSICIST

Question one

- (a) Given $P(35, 230^\circ, -7)$ in a cylindrical coordinate system, find its Cartesian and spherical coordinates. **(5 marks)**
- (b) Given a scalar function f in Cartesian system as $f = x^2 + 6y$,
- (i) find $\vec{\nabla} f$ at the point $(x = 1, y = 6, z = 0)$, **(3 marks)**
- (ii) find the directional derivative at the same point along the direction of $\vec{e}_x 3 + \vec{e}_y 4$. **(3 marks)**
- (c) Given $\vec{F} = \vec{e}_x y^2 + \vec{e}_y 5xy + \vec{e}_z 4z$, evaluate the value of the line integral $\int_L \vec{F} \cdot d\vec{l}$
- (i) if L : the straight line segment from $(0, 0)$ to $(1, 1)$ on $z = 0$ plane, **(5 marks)**
- (ii) if L is a parabolic line segment of $y = x^2$ from $(0, 0)$ to $(1, 1)$ on $z = 0$ plane, **(6 marks)**
- (iii) find $\vec{\nabla} \times \vec{F}$ and comment on whether or not the given \vec{F} is a conservative vector field. **(3 marks)**

Question two

Given $\vec{F} = \vec{e}_r r^3 + \vec{e}_\theta r^3 \sin(\phi) + \vec{e}_\phi r^3 \cos(\theta)$,

- (a) evaluate the value of the closed surface integral $\oiint_S \vec{F} \cdot d\vec{s}$ if S : the closed surface of a sphere of a radius 5 and centred at the origin, i.e.,

$$d\vec{s} = \vec{e}_r r^2 \sin(\theta) d\theta d\phi \quad \text{with } r = 5, \quad (9 \text{ marks})$$

- (b) (i) find $\vec{\nabla} \cdot \vec{F}$, (5 marks)

- (ii) find the value of the volume integral $\iiint_V (\vec{\nabla} \cdot \vec{F}) dv$ where V is the volume enclosed by the given closed surface in (a), i.e.,

$$dv = r^2 \sin(\theta) dr d\theta d\phi, \quad 0 \leq r \leq 5, \quad 0 \leq \theta \leq \pi \quad \text{and}$$

$0 \leq \phi \leq 2\pi$. Compare the result here with that obtained in (a) and make brief comment about the Divergence Theorem. (11 marks)

Question three

- (a) Given the following partial differential equation as

$$\frac{\partial^2 f(\rho, \phi)}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial f(\rho, \phi)}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 f(\rho, \phi)}{\partial \phi^2} = 0 .$$

Set $f(\rho, \phi) = F(\rho) G(\phi)$ and use the separation of variables scheme to break the given partial differential equation into two ordinary differential equations. (6 marks)

- (b) Given the following differential equation as :

$$(1 - x^2) \frac{d^2 y(x)}{dx^2} - 2x \frac{dy(x)}{dx} + 30 y(x) = 0$$

utilize the power series method , i.e., setting $y(x) = \sum_{n=0}^{\infty} a_n x^{n+s}$ and $a_0 \neq 0$,

- (i) write down the indicial equations and find the values of s and also possibly the value of a_1 , (6 marks)
- (ii) write down the recurrence relation. For each possible values of s found in (b)
- (i) , set $a_0 = 1$ and use the recurrence relation to calculate the values of a_n up to the value of a_5 , (11 marks)
- (iii) write down the general solution of the given differential equation. (2 marks)

Question four

- (a) An elastic string of length **8** is fixed at its two ends, i.e., at $x = 0$ and $x = 8$.

Given one-dimensional wave equation governing the transverse deflection of the string

$u(x, t)$ as :

$$\frac{\partial^2 u(x, t)}{\partial t^2} = 4 \frac{\partial^2 u(x, t)}{\partial x^2}$$

- (i) show that a solution of this form $u(x, t) = \sum_{n=1}^{\infty} E_n \sin\left(\frac{n\pi x}{8}\right) \cos\left(\frac{n\pi t}{4}\right)$ where E_n is an arbitrary constant satisfying two fixed end conditions as well as zero initial speed condition , (6 marks)
- (ii) if the initial position of the string , i.e., $u(x, 0)$, is given as

$$u(x, 0) = \begin{cases} \frac{5}{3}x & \text{if } 0 \leq x \leq 3 \\ -x + 8 & \text{if } 3 \leq x \leq 8 \end{cases}$$

find E_n in terms of n and calculate the values of E_1 , E_2 and E_3 .

$$\left(\text{hint : } \int_{x=0}^L \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx = \begin{cases} 0 & \text{if } n \neq m \\ \frac{L}{2} & \text{if } n = m \end{cases} \right) \quad (10 \text{ marks})$$

- (b) Given a non-homogeneous differential equation as

$$\frac{d^2 x(t)}{dt^2} - 2 \frac{dx(t)}{dt} + 3x(t) = 5 \cos(3t) \quad , \text{ set the particular solution of } x(t) \text{ as}$$

$k_1 \cos(3t) + k_2 \sin(3t)$ and determine the values of k_1 and k_2 . (9 marks)

Question five

Given the following equations for coupled oscillator system as :

$$\begin{cases} \frac{d^2 x_1(t)}{dt^2} = -11 x_1(t) + 9 x_2(t) \\ \frac{d^2 x_2(t)}{dt^2} = 3 x_1(t) - 5 x_2(t) \end{cases}$$

- (a) set $x_1(t) = X_1 e^{i\omega t}$ and $x_2(t) = X_2 e^{i\omega t}$, deduce the following matrix

equation $A X = -\omega^2 X$ where

$$A = \begin{pmatrix} -11 & 9 \\ 3 & -5 \end{pmatrix} \quad \text{and} \quad X = \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \quad (3 \text{ marks})$$

- (b) find the eigenfrequencies ω of the given coupled system, (4 marks)

- (c) find the eigenvectors X of the given coupled system corresponding to each eigenfrequencies found in (a), (5 marks)

- (d) (i) write down the general solutions for $x_1(t)$ and $x_2(t)$, (3 marks)

- (ii) if initially their positions are $x_1(0) = 0$ and $x_2(0) = 3$ and their speeds are

zero, i.e., $\left. \frac{dx_1(t)}{dt} \right|_{t=0} = \left. \frac{dx_2(t)}{dt} \right|_{t=0} = 0$, determine the values of the

arbitrary constants in (c) (i) and thus find the specific solution. (10 marks)

Useful informations

The transformations between rectangular and spherical coordinate systems are :

$$\left\{ \begin{array}{l} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{array} \right. \quad \left\{ \begin{array}{l} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1} \frac{\sqrt{x^2 + y^2}}{z} \\ \phi = \tan^{-1} \frac{y}{x} \end{array} \right.$$

The transformations between rectangular and cylindrical coordinate systems are :

$$\left\{ \begin{array}{l} x = \rho \cos \phi \\ y = \rho \sin \phi \\ z = z \end{array} \right. \quad \left\{ \begin{array}{l} \rho = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1} \frac{y}{x} \\ z = z \end{array} \right.$$

$$\bar{\nabla} f = \bar{e}_1 \frac{1}{h_1} \frac{\partial f}{\partial u_1} + \bar{e}_2 \frac{1}{h_2} \frac{\partial f}{\partial u_2} + \bar{e}_3 \frac{1}{h_3} \frac{\partial f}{\partial u_3}$$

$$\bar{\nabla} \cdot \bar{F} = \frac{1}{h_1 h_2 h_3} \left(\frac{\partial(F_1 h_2 h_3)}{\partial u_1} + \frac{\partial(F_2 h_1 h_3)}{\partial u_2} + \frac{\partial(F_3 h_1 h_2)}{\partial u_3} \right)$$

$$\begin{aligned} \bar{\nabla} \times \bar{F} = & \frac{\bar{e}_1}{h_2 h_3} \left(\frac{\partial(F_3 h_3)}{\partial u_2} - \frac{\partial(F_2 h_2)}{\partial u_3} \right) + \frac{\bar{e}_2}{h_1 h_3} \left(\frac{\partial(F_1 h_1)}{\partial u_3} - \frac{\partial(F_3 h_3)}{\partial u_1} \right) \\ & + \frac{\bar{e}_3}{h_1 h_2} \left(\frac{\partial(F_2 h_2)}{\partial u_1} - \frac{\partial(F_1 h_1)}{\partial u_2} \right) \end{aligned}$$

where $\bar{F} = \bar{e}_1 F_1 + \bar{e}_2 F_2 + \bar{e}_3 F_3$ and

(u_1, u_2, u_3) represents (x, y, z) for rectangular coordinate system

represents (ρ, ϕ, z) for cylindrical coordinate system

represents (r, θ, ϕ) for spherical coordinate system

$(\bar{e}_1, \bar{e}_2, \bar{e}_3)$ represents $(\bar{e}_x, \bar{e}_y, \bar{e}_z)$ for rectangular coordinate system

represents $(\bar{e}_\rho, \bar{e}_\phi, \bar{e}_z)$ for cylindrical coordinate system

represents $(\bar{e}_r, \bar{e}_\theta, \bar{e}_\phi)$ for spherical coordinate system

(h_1, h_2, h_3) represents $(1, 1, 1)$ for rectangular coordinate system

represents $(1, \rho, 1)$ for cylindrical coordinate system

represents $(1, r, r \sin \theta)$ for spherical coordinate system