

**UNIVERSITY OF SWAZILAND**

**FACULTY OF SCIENCE**

**DEPARTMENT OF PHYSICS**

**MAIN EXAMINATION 2008/2009**

**TITLE OF PAPER : MATHEMATICAL METHODS FOR  
PHYSICISTS**

**COURSE NUMBER : P272**

**TIME ALLOWED : THREE HOURS**

**INSTRUCTIONS : ANSWER ANY FOUR OUT OF SIX  
QUESTIONS.  
EACH QUESTION CARRIES 25 MARKS.**

**MARKS FOR DIFFERENT SECTIONS ARE  
SHOWN IN THE RIGHT-HAND MARGIN.**

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**P272 MATHEMATICAL METHODS FOR PHYSICIST**

**Question one**

(a) Given  $P(-5, -3, -7)$  in Cartesian coordinate system, find its cylindrical and spherical coordinates. **(5 marks)**

(b) Given a scalar function  $f$  in Cartesian system as  $f = 7x^2 - 5xy + z^2$ , find  $\nabla f$  at the point  $P(x=2, y=-3, z=1)$ , **(4 marks)**

(c) Given a vector field  $\vec{F} = \vec{e}_x 2xy + \vec{e}_y (x^2 - 12yz) - \vec{e}_z 6y^2$ , find the value of line integral of  $\vec{F}$  from the point  $P_1 : (1, 2, 0)$  to the point

$P_2 : (5, 14, 0)$  along a line path of  $L$ , i.e.,  $\int_{P_1, L}^{P_2} \vec{F} \cdot d\vec{l}$ ,

(i) if  $L$  is a straight line from  $P_1$  to  $P_2$ , **(8 marks)**

(ii) if  $L$  is a parabolic path from  $P_1$  to  $P_2$  described by  $y = \frac{1}{2}x^2 + \frac{3}{2}$

on  $z = 0$  plane. Compare this result with that obtained in (c)(i) and make a brief comment on whether the given  $\vec{F}$  is a conservative vector field or not?

**(8 marks)**

### Question two

Given a vector field  $\vec{F} = \vec{e}_r 5r^2 - \vec{e}_\theta r^2 + \vec{e}_\phi r^2 \sin(\phi)$

- (a) evaluate the value of the closed surface integral  $\oiint_S \vec{F} \cdot d\vec{s}$  if  $S$  the closed surface of a sphere of a radius 4 and centred at the origin, i.e.,

$$d\vec{s} = \vec{e}_r r^2 \sin(\theta) d\theta d\phi$$

$\xrightarrow{r=4} \vec{e}_r 16 \sin(\theta) d\theta d\phi$  ,  $0 \leq \theta \leq \pi$  &  $0 \leq \phi \leq 2\pi$

( 9 marks )

- (b) (i) find  $\vec{\nabla} \cdot \vec{F}$  ,

( 5 marks )

- (ii) find the value of the volume integral  $\iiint_V (\vec{\nabla} \cdot \vec{F}) dV$  where  $V$  is the volume enclosed by the given closed surface in (a), i.e.,

$$dV = r^2 \sin(\theta) dr d\theta d\phi , 0 \leq r \leq 4 , 0 \leq \theta \leq \pi \text{ \& } 0 \leq \phi \leq 2\pi$$

Compare the result here with that obtained in (a) and make brief comment about the Divergence Theorem.

( 11 marks )

### Question three

Given the following differential equation as :

$$\frac{d^2 y(x)}{dx^2} - \frac{dy(x)}{dx} + 3y(x) = 0$$

utilize the power series method , i.e., setting  $y(x) = \sum_{n=0}^{\infty} a_n x^{n+s}$  and  $a_0 \neq 0$  ,

- (a) write down the indicial equations. Find the values of  $s$  and  $a_1$  (by setting  $a_0 = 1$ ) .

**( 10 marks )**

- (b) write down the recurrence relation. For all the appropriate values of  $s$  and  $a_1$  found in

(a), set  $a_0 = 1$  and use the recurrence relation to calculate the values of  $a_n$  up to the

value of  $a_5$  . Thus write down two independent solution in their polynomial forms.

**( 15 marks )**

### Question four

An elastic string of length 10 is fixed at its two ends, i.e., at  $x = 0$  &  $x = 10$  and its transverse deflection  $u(x, t)$  satisfies the following one-dimensional wave equation

$$\frac{\partial^2 u(x, t)}{\partial t^2} = 9 \frac{\partial^2 u(x, t)}{\partial x^2},$$

- (a) use separation of variable scheme to split the above partial differential equation into two ordinary differential equations and then write down the general solution of  $u(x, t)$ .

( 8 marks )

- (b) given the general solution of  $u(x, t)$ , after satisfying two fixed end conditions as well as

zero initial speed condition, as  $u(x, t) = \sum_{n=1}^{\infty} E_n \sin\left(\frac{n\pi x}{10}\right) \cos\left(\frac{3n\pi t}{10}\right)$  where

$E_n$   $n = 1, 2, 3, \dots$  are arbitrary constants, then find  $E_n$  in terms of  $n$  and

calculate the values of  $E_1$ ,  $E_2$  &  $E_3$  if the initial position of the string, i.e.,  $u(x, 0)$ ,

is given as 
$$u(x, 0) = \begin{cases} 4x & \text{if } 0 \leq x \leq 2 \\ -x + 10 & \text{if } 2 \leq x \leq 10 \end{cases}$$

(hint :  $\int_{x=0}^{10} \sin\left(\frac{n\pi x}{10}\right) \sin\left(\frac{m\pi x}{10}\right) dx = \begin{cases} 0 & \text{if } n \neq m \\ 5 & \text{if } n = m \end{cases}$  &

$\int x \sin\left(\frac{n\pi x}{10}\right) dx = \frac{100}{n^2 \pi^2} \sin\left(\frac{n\pi x}{10}\right) - \frac{10}{n\pi} x \cos\left(\frac{n\pi x}{10}\right)$  ) ( 17 marks )

### Question five

Given the following equations for coupled oscillator system as :

$$\begin{cases} \frac{d^2 x_1(t)}{dt^2} = -5 x_1(t) + 16 x_2(t) \\ \frac{d^2 x_2(t)}{dt^2} = 4 x_1(t) - 17 x_2(t) \end{cases}$$

(a) set  $x_1(t) = X_1 e^{i\omega t}$  &  $x_2(t) = X_2 e^{i\omega t}$ , deduce the following matrix

equation  $A X = -\omega^2 X$  where

$$A = \begin{pmatrix} -5 & 16 \\ 4 & -17 \end{pmatrix} \quad \& \quad X = \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \quad (5 \text{ marks})$$

(b) find the eigenfrequencies  $\omega$  of the given coupled system, (6 marks)

(c) find the eigenvectors  $X$  of the given coupled system corresponding to each eigenfrequencies found in (b), (8 marks)

(d) find the normal coordinates of the given coupled system. (6 marks)

### Question six

Given the following non-homogeneous differential equation as :

$$\frac{d^2 x(t)}{dt^2} + 2 \frac{dx(t)}{dt} + 5 x(t) = 8 e^{-t} + 26 \sin(3t)$$

- (a) set its particular solution as  $x_p(t) = k_1 e^{-t} + k_2 \sin(3t) + k_3 \cos(3t)$  , determine the values of  $k_1$  ,  $k_2$  &  $k_3$  . ( 9 marks )

- (b) find the general solution to the homogeneous part of the given differential equation , i.e.,

$$\frac{d^2 x(t)}{dt^2} + 2 \frac{dx(t)}{dt} + 5 x(t) = 0 , \text{ and name it as } x_h(t) . \quad ( 6 \text{ marks } )$$

- (c) write the general solution to the given non-homogeneous differential equation as

$x(t) = x_p(t) + x_h(t)$  and determine the values of the arbitrary constants in this general

solution if the initial conditions are given as  $x(0) = 5$  &  $\left. \frac{dx(t)}{dt} \right|_{t=0} = 0$  .

( 10 marks )

### Useful informations

The transformations between rectangular and spherical coordinate systems are :

$$\left\{ \begin{array}{l} x = r \sin(\theta) \cos(\phi) \\ y = r \sin(\theta) \sin(\phi) \\ z = r \cos(\theta) \end{array} \right. \quad \& \quad \left\{ \begin{array}{l} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1} \left( \frac{\sqrt{x^2 + y^2}}{z} \right) \\ \phi = \tan^{-1} \left( \frac{y}{x} \right) \end{array} \right.$$

The transformations between rectangular and cylindrical coordinate systems are :

$$\left\{ \begin{array}{l} x = \rho \cos(\phi) \\ y = \rho \sin(\phi) \\ z = z \end{array} \right. \quad \& \quad \left\{ \begin{array}{l} \rho = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1} \left( \frac{y}{x} \right) \\ z = z \end{array} \right.$$

$$\bar{\nabla} f = \bar{e}_1 \frac{1}{h_1} \frac{\partial f}{\partial u_1} + \bar{e}_2 \frac{1}{h_2} \frac{\partial f}{\partial u_2} + \bar{e}_3 \frac{1}{h_3} \frac{\partial f}{\partial u_3}$$

$$\bar{\nabla} \cdot \bar{F} = \frac{1}{h_1 h_2 h_3} \left( \frac{\partial(F_1 h_2 h_3)}{\partial u_1} + \frac{\partial(F_2 h_1 h_3)}{\partial u_2} + \frac{\partial(F_3 h_1 h_2)}{\partial u_3} \right)$$

$$\begin{aligned} \bar{\nabla} \times \bar{F} = & \frac{\bar{e}_1}{h_2 h_3} \left( \frac{\partial(F_3 h_3)}{\partial u_2} - \frac{\partial(F_2 h_2)}{\partial u_3} \right) + \frac{\bar{e}_2}{h_1 h_3} \left( \frac{\partial(F_1 h_1)}{\partial u_3} - \frac{\partial(F_3 h_3)}{\partial u_1} \right) \\ & + \frac{\bar{e}_3}{h_1 h_2} \left( \frac{\partial(F_2 h_2)}{\partial u_1} - \frac{\partial(F_1 h_1)}{\partial u_2} \right) \end{aligned}$$

where  $\bar{F} = \bar{e}_1 F_1 + \bar{e}_2 F_2 + \bar{e}_3 F_3$  and

$(u_1, u_2, u_3)$	represents	$(x, y, z)$	for rectangular coordinate system
	represents	$(\rho, \phi, z)$	for cylindrical coordinate system
	represents	$(r, \theta, \phi)$	for spherical coordinate system

$(\bar{e}_1, \bar{e}_2, \bar{e}_3)$	represents	$(\bar{e}_x, \bar{e}_y, \bar{e}_z)$	for rectangular coordinate system
	represents	$(\bar{e}_\rho, \bar{e}_\phi, \bar{e}_z)$	for cylindrical coordinate system
	represents	$(\bar{e}_r, \bar{e}_\theta, \bar{e}_\phi)$	for spherical coordinate system

$(h_1, h_2, h_3)$	represents	$(1, 1, 1)$	for rectangular coordinate system
	represents	$(1, \rho, 1)$	for cylindrical coordinate system
	represents	$(1, r, r \sin(\theta))$	for spherical coordinate system