## UNIVERSITY OF SWAZILAND

## FACULTY OF SCIENCE AND ENGINEERING

## DEPARTMENT OF PHYSICS

MAIN EXAMINATION $\quad 2012 / 2013$
TITLE OF PAPER : MATHEMATICAL METHODS FOR PHYSICISTS
COURSE NUMBER : P272
TIME ALLOWED : THREE HOURS
INSTRUCTIONS : ANSWER ANY FOUR OUT OF SIX QUESTIONS. EACH QUESTION CARRIES 25 MARKS.MARKS FOR DIFFERENT SECTIONS ARESHOWN IN THE RIGHT-HAND MARGIN.

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## P272 MATHEMATICAL METHODS FOR PHYSICIST

## Question one

(a) Given a vector field in Cartesian coordinates as $\vec{F}=\vec{e}_{x} 5 x y z-\vec{e}_{z} 4 x^{2} y$, show that it satisfies the following vector identity $\vec{\nabla} \bullet(\vec{\nabla} \times \vec{F}) \equiv 0$.
( 6 marks)
(b) Given $\vec{F}=\vec{e}_{x}(-6 x z)+\vec{e}_{y}\left(6 y^{2}\right)+\vec{e}_{z}\left(-3 x^{2}\right)$ find the value of the following line integral
$\int_{P_{1}, L}^{P_{2}} \vec{F} \bullet d \vec{l} \quad$ if $\mathrm{P}_{1}:(-2,-2,1), \mathrm{P}_{2}:(2,2,1)$ and
(i) $L$ : a straight line from $P_{1}$ to $P_{2}$ on $z=1$ plane.
( 6 marks)
(ii) L : a semi-circular path in counter clockwise sense from $P_{1}$ to $P_{2}$ on $z=1$ plane, centred at $(0,0,1)$ with a radius of $2 \sqrt{2}$.
Compare this answer with that obtained in (b)(i) and show that the given $\vec{F}$ is a conservative vector field.
( 10 marks)
(Hint : L: $z=1, x=2 \sqrt{2} \cos (\mathrm{t}), \mathrm{y}=2 \sqrt{2} \sin (\mathrm{t}) \& \mathrm{t}$ from $\pi+\frac{\pi}{4}$ to $\frac{\pi}{4}$ )
(iii) Show that the associated scalar potential $f$ of this given conservative vector field is $\quad f=2 y^{3}-3 x^{2} z$.
( 3 marks)

## Question two

Given $\vec{F}=\vec{e}_{\rho}\left(4 \rho^{3}\right)+\vec{e}_{\phi}\left(\rho^{3} \sin \phi\right)+\vec{e}_{z}\left(2 \rho z^{2}\right)$ in cylindrical coordinates,
(a) find the value of $\oint_{S} \vec{F} \bullet d \vec{s}$ if $S$ is the closed surface enclosing the cylindrical tube of cross-sectional radius 5 and tube height 9 , i.e., $S=S_{1}+S_{2}+S_{3}$ where
$\mathrm{S}_{1}:\left(z=-3,0 \leq \rho \leq 5,0 \leq \phi \leq 2 \pi \quad \& \quad d \vec{s}=-\vec{e}_{z} \rho d \rho d \phi\right)$
$\mathrm{S}_{2}:\left(z=+6,0 \leq \rho \leq 5,0 \leq \phi \leq 2 \pi \quad \& \quad d \vec{s}=+\bar{e}_{z} \rho d \rho d \phi\right)$
$\mathrm{S}_{3}:\left(\rho=5,0 \leq \phi \leq 2 \pi,-3 \leq z \leq+6 \& d \vec{s}=\vec{e}_{\rho} \rho d \phi d z \xrightarrow{\rho=5} \vec{e}_{\rho} 5 d \phi d z\right)$
( 13 marks )
(b) (i) find $\vec{\nabla} \bullet \vec{F}$,
( 4 marks)
(ii) then evaluate the value of $\iiint_{V}(\vec{\nabla} \bullet \vec{F}) d v$ where V is bounded by S given in (a), i.e., V : $0 \leq \rho \leq 5,0 \leq \phi \leq 2 \pi,-3 \leq z \leq+6$ \& $d v=\rho d \rho d \phi d z$. Compare this value with that obtained in (a) and make a brief comment.
( 8 marks)

## Question three

Given the following non-homogeneous differential equation as
$\frac{d^{2} x(t)}{d t^{2}}+2 \frac{d x(t)}{d t}+5 x(t)=f(t)$,
(a) find its particular solution $x_{p}(t)$ if
(i) $\quad f(t)=26 \sin (3 t)$
( 6 marks)
(ii) $f(t)=5 t$,
( 5 marks)
(b) for the homogeneous part of the given non-homogeneous differential equation, i.e., $\frac{d^{2} x(t)}{d t^{2}}+2 \frac{d x(t)}{d t}+5 x(t)=0$, set $x(t)=e^{\alpha t}$ and find the appropriate values of $\alpha$ and thus write down its general solution $x_{h}(t)$
(c) if $f(t)=26 \sin (3 t)$, write down the general solution of the given non-homogeneous differential equation in terms of the answers obtained in (a) \& (b). If the initial conditions are $x(0)=\left.2 \& \frac{d x(t)}{d t}\right|_{t=0}=1$, find its specific solution $x_{s}(t)$.

## Question four

(a) Given the following 2-D Laplace equation in spherical coordinates as
$\nabla^{2} f(r, \theta)=\frac{1}{r^{2}} \frac{\partial}{\partial r}\left(r^{2} \frac{\partial f(r, \theta)}{\partial r}\right)+\frac{1}{r^{2} \sin (\theta)} \frac{\partial}{\partial \theta}\left(\sin (\theta) \frac{\partial f(r, \theta)}{\partial \theta}\right)=0 \quad$, set $f(r, \theta)=F(r) G(\theta)$ and use separation variable scheme to separate the above partial differential equation into two ordinary differential equations.
(b) Given a Bessel's differential equation as :
$x^{2} \frac{d^{2} y(x)}{d x^{2}}+x \frac{d y(x)}{d x}+\left(x^{2}-9\right) y(x)=0$, set $\quad y(x)=\sum_{n=0}^{\infty} a_{n} x^{n+s} \quad \& \quad a_{0} \neq 0$ and utilize the power series method,
(i) write down its indicial equations and show that $s=-3$ or +3 and $a_{1}=0$,
( 8 marks)
(ii) write down its recurrence relation. Set $a_{0}=1$ and use the recurrence relation to generate two independent solutions in power series form truncated up to $a_{6}$ term. Show that one of the independent solution is a divergent series.

## Question five

Two simple harmonic oscillators are joined by a spring with a spring constant $k_{12}$ as shown in the diagram below :


The equations of motion for this coupled oscillator system ignoring friction are given as
$\left\{\begin{array}{l}m_{1} \frac{d^{2} x_{1}(t)}{d t^{2}}=-\left(k_{1}+k_{12}\right) x_{1}(t)+k_{12} x_{2}(t) \\ m_{2} \frac{d^{2} x_{2}(t)}{d t^{2}}=k_{12} x_{1}(t)-\left(k_{2}+k_{12}\right) x_{2}(t)\end{array}\right.$
where $x_{1} \& x_{2}$ are horizontal displacements of $m_{1} \& m_{2}$ measured from their respective resting positions.
If given $m_{1}=1 \mathrm{~kg}, m_{2}=3 \mathrm{~kg}, k_{1}=2 \frac{\mathrm{~N}}{\mathrm{~m}}, k_{2}=6 \frac{\mathrm{~N}}{\mathrm{~m}} \& k_{12}=9 \frac{\mathrm{~N}}{\mathrm{~m}}$,
(a) Set $x_{1}(t)=X_{1} e^{i \omega t} \quad \& \quad x_{2}(t)=X_{2} e^{i \omega t}$, then the above given equations can be deduced to the following matrix equation $A X=-\omega^{2} X \quad$ where

$$
A=\left(\begin{array}{cc}
-11 & 9  \tag{5marks}\\
3 & -5
\end{array}\right) \quad \& \quad X=\binom{X_{1}}{X_{2}}
$$

(b) find the eigenfrequencies $\omega$ of the given coupled system,
(c) find the eigenvectors X of the given coupled system corresponding to each eigenfrequencies found in (b),
(d) find the normal coordinates of the given coupled system,
(e) write down the general solutions for $x_{1}(t) \& x_{2}(t)$.

## Question six

An elastic string of length 8 is fixed at its two ends, i.e., at $x=0 \quad \& \quad x=8$ and its transverse deflection $u(x, t)$ satisfies the following one-dimensional wave equation $\frac{\partial^{2} u(x, t)}{\partial t^{2}}=4 \frac{\partial^{2} u(x, t)}{\partial x^{2}}$,
(a) use separation of variable scheme to split the above partial differential equation into two ordinary differential equations and then write down the general solution of $u(x, t)$.
( 8 marks)
(b) given the general solution of $u(x, t)$, after satisfying two fixed end conditions as well as zero initial speed condition, as $\quad u(x, t)=\sum_{n=1}^{\infty} E_{n} \sin \left(\frac{n \pi x}{8}\right) \cos \left(\frac{n \pi t}{4}\right) \quad$ where $E_{n} \quad n=1,2,3, \cdots \cdots \quad$ are arbitrary constants, then find $E_{n}$ in terms of $n$ and calculate the values of $E_{1}, E_{2} \& E_{3}$ if the initial position of the string, i.e., $u(x, 0)$, is given as $\quad u(x, 0)=\left\{\begin{array}{cl}3 x & \text { if } 0 \leq x \leq 2 \\ -x+8 & \text { if } 2 \leq x \leq 8\end{array}\right.$
(hint: $\int_{x=0}^{8} \sin \left(\frac{n \pi x}{8}\right) \sin \left(\frac{m \pi x}{8}\right) d x=\left\{\begin{array}{lll}0 & \text { if } & n \neq m \\ 4 & \text { if } & n=m\end{array} \quad \&\right.$
$\left.\int x \sin \left(\frac{n \pi x}{8}\right) d x=\frac{64}{n^{2} \pi^{2}} \sin \left(\frac{n \pi x}{8}\right)-\frac{8}{n \pi} x \cos \left(\frac{n \pi x}{8}\right)\right)$
( 17 marks)

## Useful informations

The transformations between rectangular and spherical coordinate systems are :

$$
\left\{\begin{array} { c } 
{ x = r \operatorname { s i n } ( \theta ) \operatorname { c o s } ( \phi ) } \\
{ y = r \operatorname { s i n } ( \theta ) \operatorname { s i n } ( \phi ) } \\
{ z = r \operatorname { c o s } ( \theta ) }
\end{array} \quad \& \quad \left\{\begin{array}{c}
r=\sqrt{x^{2}+y^{2}+z^{2}} \\
\theta=\tan ^{-1}\left(\frac{\sqrt{x^{2}+y^{2}}}{z}\right) \\
\phi=\tan ^{-1}\left(\frac{y}{x}\right)
\end{array}\right.\right.
$$

The transformations between rectangular and cylindrical coordinate systems are :

$$
\begin{aligned}
& \left\{\begin{array} { l } 
{ x = \rho \operatorname { c o s } ( \phi ) } \\
{ y = \rho \operatorname { s i n } ( \phi ) } \\
{ z = z }
\end{array} \quad \& \quad \left\{\begin{array}{c}
\rho=\sqrt{x^{2}+y^{2}} \\
\phi=\tan ^{-1}\left(\frac{y}{x}\right) \\
z=z
\end{array}\right.\right. \\
& \vec{\nabla} f=\vec{e}_{1} \frac{1}{h_{1}} \frac{\partial f}{\partial u_{1}}+\vec{e}_{2} \frac{1}{h_{2}} \frac{\partial f}{\partial u_{2}}+\vec{e}_{3} \frac{1}{h_{3}} \frac{\partial f}{\partial u_{3}}
\end{aligned} \begin{aligned}
& \vec{\nabla} \bullet \vec{F}=\frac{1}{h_{1} h_{2} h_{3}}\left(\frac{\partial\left(F_{1} h_{2} h_{3}\right)}{\partial u_{1}}+\frac{\partial\left(F_{2} h_{1} h_{3}\right)}{\partial u_{2}}+\frac{\partial\left(F_{3} h_{1} h_{2}\right)}{\partial u_{3}}\right) \\
& \vec{\nabla} \times \vec{F}= \frac{\vec{e}_{1}}{h_{2} h_{3}}\left(\frac{\partial\left(F_{3} h_{3}\right)}{\partial u_{2}}-\frac{\partial\left(F_{2} h_{2}\right)}{\partial u_{3}}\right)+\frac{\vec{e}_{2}}{h_{1} h_{3}}\left(\frac{\partial\left(F_{1} h_{1}\right)}{\partial u_{3}}-\frac{\partial\left(F_{3} h_{3}\right)}{\partial u_{1}}\right) \\
& \quad+\frac{\vec{e}_{3}}{h_{1} h_{2}}\left(\frac{\partial\left(F_{2} h_{2}\right)}{\partial u_{1}}-\frac{\partial\left(F_{1} h_{1}\right)}{\partial u_{2}}\right)
\end{aligned}
$$

where $\vec{F}=\vec{e}_{1} F_{1}+\vec{e}_{2} F_{2}+\vec{e}_{3} F_{3} \quad$ and $\left(u_{1}, u_{2}, u_{3}\right)$ represents $(x, y, z) \quad$ for rectangular coordinate system represents $\quad(\rho, \phi, z) \quad$ for cylindrical coordinate system represents $(r, \theta, \phi) \quad$ for spherical coordinate system $\left(\vec{e}_{1}, \vec{e}_{2}, \vec{e}_{3}\right)$ represents $\left(\vec{e}_{x}, \vec{e}_{y}, \vec{e}_{z}\right) \quad$ for rectangular coordinate system represents $\left(\vec{e}_{\rho}, \vec{e}_{\phi}, \vec{e}_{z}\right) \quad$ for cylindrical coordinate system represents $\left(\vec{e}_{r}, \vec{e}_{\theta}, \vec{e}_{\phi}\right) \quad$ for spherical coordinate system

$$
\begin{array}{lll}
\left(h_{1}, h_{2}, h_{3}\right) & \text { represents } & (1,1,1) \\
& \text { represents } & (1, \rho, 1) \\
& \text { represents } & (1, r, r \sin (\theta))
\end{array}
$$ for rectangular coordinate system for cylindrical coordinate system for spherical coordinate system

$\int(t \sin (k t)) d t=-\frac{t \cos (k t)}{k}+\frac{\sin (k t)}{k^{2}}$
$\int(t \cos (k t)) d t=\frac{t \sin (k t)}{k}+\frac{\cos (k t)}{k^{2}}$

