## UNIVERSITY OF SWAZILAND

FACULTY OF SCIENCE AND ENGINEERING
DEPARTMENT OF PHYSICS
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TITLE OF PAPER : MATHEMATICAL METHODS FOR PHYSICISTS
COURSE NUMBER : P272
TIME ALLOWED : THREE HOURS
INSTRUCTIONS : ANSWER ANY FOUR OUT OF FIVE QUESTIONS. EACH QUESTION CARRIES 25 MARKS.
MARKS FOR DIFFERENT SECTIONS ARE SHOWN IN THE RIGHT-HAND MARGIN.

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## P272 MATHEMATICAL METHODS FOR PHYSICIST

## Question one

Given a vector field $\vec{F}=\vec{e}_{x}\left(x^{2}\right)+\vec{e}_{y}\left(y^{2}-x z\right)+\vec{e}_{z}\left(x^{2}\right)$ in Cartesian coordinates,
(a) find the value of $\int_{P_{1}, L}^{P_{2}} \vec{F} \bullet d \vec{l}$ if $P_{1}:(0,0,1), P_{2}:(2,8,1)$ and
(i) $\quad L$ : a straight line from $P_{1}$ to $P_{2}$ on $z=1$ plane,
( 6 marks )
(ii) $L$ : a cubic curve $y=x^{3}$ from $P_{1}$ to $P_{2}$ on $z=1$ plane.

Then compare this answer with that obtained in (a)(i) and comment on whether the given $\vec{F}$ is a conservative vector field or not.
( 6+1 marks )
(iii) Find $\vec{\nabla} \times \vec{F}$. Does it agree with your comment in (a)(ii)?
( $3+1$ marks)
(b) Choose a closed surface $S$ as the cover surface of a rectangular box of dimension $1 \times 2 \times 3$ with its two opposite vertex points as $(0,0,0)$ and $(1,2,3)$ as show in the diagram below :


Utilize the Divergence theorem to find the value of $\oint_{\delta} \vec{F} \bullet d \vec{s}$, i.e., instead of doing the closed surface integral to find the answer, you can do the volume integral about the volume $V$ which is bounded by the chosen closed surface $S$ to find the same answer. Here doing the volume integral is much easier than that doing the closed surface integral.
( $S=S_{1}+S_{2}+S_{3}+S_{4}+S_{5}+S_{6} \quad$ where
$S_{1}: z=3,0 \leq x \leq 1,0 \leq y \leq 2 \& d \vec{s}=+\vec{e}_{z}(d x)(d y)$
$S_{2}: z=0,0 \leq x \leq 1,0 \leq y \leq 2 \& d \vec{s}=-\vec{e}_{z}(d x)(d y)$
$S_{3}: y=0,0 \leq x \leq 1,0 \leq z \leq 3 \& d \vec{s}=-\vec{e}_{y}(d x)(d z)$
$S_{4}: y=2,0 \leq x \leq 1,0 \leq z \leq 3 \& d \vec{s}=+\vec{e}_{y}(d x)(d z)$
$S_{5}: x=1,0 \leq y \leq 2,0 \leq z \leq 3 \& d \vec{s}=+\vec{e}_{x}(d y)(d z)$
$S_{6}: x=0,0 \leq y \leq 2,0 \leq z \leq 3 \& d \vec{s}=-\vec{e}_{x}(d y)(d z)$
$V:(0 \leq x \leq 1,0 \leq y \leq 2,0 \leq y \leq 2 \& d v=(d x)(d y)(d z))$

## Question two

Given $\vec{F}=\vec{e}_{\rho}\left(z^{2} \cos (\phi)\right)+\vec{e}_{\phi}\left(\rho^{2}\right)+\vec{e}_{z}\left(\rho^{2} \sin (\phi)\right)$ in cylindrical coordinates,
(a) find the value of $\oint \vec{F} \bullet d \vec{l}$ if $L$ is the circular closed loop of radius 10 on $z=0 \quad$ plane in counter clockwise sense as shown in the diagram below

ie., $\quad L:\left(\rho=10,0 \leq \phi \leq 2 \pi, \theta=\frac{\pi}{2} \& d \vec{l}=+\vec{e}_{\phi} \rho d \phi \xrightarrow{\rho=10} \vec{e}_{\phi} 10 d \phi\right)$
( 6 marks)
(b) (i) Find $\vec{\nabla} \times \vec{F}$ and show that

$$
\vec{\nabla} \times \vec{F}=\vec{e}_{\rho}(\rho \cos (\phi))+\vec{e}_{\phi}(2 z \cos (\phi)-2 \rho \sin (\phi))+\vec{e}_{z}\left(3 \rho^{2}+\frac{z^{2} \sin (\phi)}{\rho}\right)
$$

( 5 marks)
(ii) Evaluate the value of $\iint_{S}(\vec{\nabla} \times \vec{F}) \cdot d \vec{s}$ where $S$ is bounded by $L$ given in (a), ie., $S$ : $\left(0 \leq \rho \leq 10,0 \leq \phi \leq 2 \pi, z=0 \quad \& \quad d \vec{s}=+\vec{e}_{z} \rho d \rho d \phi\right)$. Compare this value with that obtained in (a) and make a brief comment.
(8+1 marks)
(c) Find $\vec{\nabla} \bullet(\vec{\nabla} \times \vec{F})$ and show that it is zero.

## Question three

Given the following Legendre differential equation as :
$\left(1-x^{2}\right) \frac{d^{2} y(x)}{d x^{2}}-2 x \frac{d y(x)}{d x}+20 y(x)=0$
(a) utilize the power series method, i.e., setting $y(x)=\sum_{n=0}^{\infty} a_{n} x^{n+s}$ and $a_{0} \neq 0$,
(i) write down the indicial equations. Deduce that $s=0$ or 1 and $a_{1}=0$.
( 10 marks )
(ii) Write down the recurrence relation. For $s=0$ case with $a_{1}=0$, set $a_{0}=1$ and use the recurrence relation to calculate the values of $a_{n}$ up to the value of $a_{8}$. Without further calculations, what would be the values of the rest of $a_{n}$ for $n>8$ and give a brief explanation. Thus write down this independent solution in its power series form for all $n$.
( $1+10+2$ marks)
(b) The given differential equation in (a) has a well-known polynomial solution $P_{4}(x)$ which is $P_{4}(x)=\frac{3}{8}+\frac{35}{8} x^{4}-\frac{15}{4} x^{2}$. Show that $P_{4}(x)$ is linearly dependent to the solution you obtained in (a)(ii).

## Question four

Given the following periodic function $f(t)$ of period 6 and plotted for two periods from $t=0$ to $t=12$ as below:

i.e., for one period of $t=0$ to $t=6, f(t)$ can be wholly described as :
$f(t)=\left\{\begin{array}{cccc}t & \text { if } & 0<t<3 \\ -t+6 & \text { if } & 3<t<6\end{array}\right.$
(a) Its Fourier series representation is $f(t)=\sum_{n=0}^{\infty} a_{n} \cos \left(\frac{n \pi t}{3}\right)+\sum_{n=1}^{\infty} b_{n} \sin \left(\frac{n \pi t}{3}\right)$.
(i) What special property of the given $f(t)$ implies that all the Fourier sine series coefficients should be zero, i.e., $b_{n}=0 \quad \forall n$.
( 2 mark)
(ii) Find all the Fourier cosine series coefficients and show that

$$
\begin{aligned}
& a_{0}=\frac{3}{2} \quad \& \\
& a_{n}=\frac{6(\cos (n \pi)-1)}{n^{2} \pi^{2}} \quad n=1,2,3, \cdots \cdots
\end{aligned}
$$

Thus the Fourier series representation of the given $f(t)$ is

$$
f(t)=\frac{3}{2}+\sum_{n=1}^{\infty} \frac{6(\cos (n \pi)-1)}{n^{2} \pi^{2}} \cos \left(\frac{n \pi t}{3}\right) \ldots \ldots
$$

(b) If the above given $f(t)$ is the non-homogeneous term for the following non-homogeneous differential equation $\frac{d^{2} y(t)}{d t^{2}}-\frac{d y(t)}{d t}+y(t)=f(t)$, find the particular solution $y_{p}(t)$ to the given periodical $f(t)$ represented by its Fourier series in (a)(ii), i.e., eq.(1), and show that

$$
\begin{aligned}
& y_{p}(t)=\frac{3}{2}+\sum_{n=1}^{\infty}\left(A_{n} \cos \left(\frac{n \pi t}{3}\right)+B_{n} \sin \left(\frac{n \pi t}{3}\right)\right) \quad \text { where } \\
& \left\{\begin{array}{l}
A_{n}=-\frac{9\left(n^{2} \pi^{2}-9\right)}{\left(n^{4} \pi^{4}-9 n^{2} \pi^{2}+81\right)} a_{n} \\
B_{n}=-\frac{27 n \pi}{\left(n^{4} \pi^{4}-9 n^{2} \pi^{2}+81\right)} a_{n}
\end{array}\right.
\end{aligned}
$$

## Question five

Given the following equations for coupled oscillator system as :
$\left\{\begin{array}{l}\frac{d^{2} x_{1}(t)}{d t^{2}}=-10 x_{1}(t)+6 x_{2}(t) \\ \frac{d^{2} x_{2}(t)}{d t^{2}}=2 x_{1}(t)-11 x_{2}(t)\end{array}\right.$
(a) set $x_{1}(t)=X_{1} e^{i \omega t} \quad \& \quad x_{2}(t)=X_{2} e^{i \omega t}$, deduce the following matrix equation $A X=-\omega^{2} X$ where
$A=\left(\begin{array}{cc}-10 & 6 \\ 2 & -11\end{array}\right) \quad \& \quad X=\binom{X_{1}}{X_{2}}$
(b) Find the eigenfrequencies $\omega$ of the given coupled system and show that they are $\omega_{1}=\sqrt{7} \& \omega_{2}=\sqrt{14}$,
(c) Find the eigenvectors $X$ of the given coupled system corresponding to each eigenfrequencies found in (b),
( 6 marks )
(d) Find the normal coordinates $x_{1}{ }^{\prime}(t) \& x_{2}{ }^{\prime}(t)$ of the given coupled system and show that one of the possible answers is
$\left\{\begin{array}{l}x_{1}{ }^{\prime}(t)=2 x_{1}(t)+3 x_{2}(t) \\ x_{2}{ }^{\prime}(t)=x_{1}(t)-2 x_{2}(t)\end{array}\right.$
(Note : Normal coordinates just like eigenvectors, they are not unique. Any constant times the answer can be another possible answer.)
( 8 marks)
(e) Write down the general solution of the given system in terms of the eigenfrequencies and eigenvectors obtained in (b) \& (c).
( 2 marks)

## Useful informations

The transformations between rectangular and spherical coordinate systems are :
$\left\{\begin{array}{c}x=r \sin (\theta) \cos (\phi) \\ y=r \sin (\theta) \sin (\phi) \\ z=r \cos (\theta)\end{array} \quad \& \quad\left\{\begin{array}{c}r=\sqrt{x^{2}+y^{2}+z^{2}} \\ \theta=\tan ^{-1}\left(\frac{\sqrt{x^{2}+y^{2}}}{z}\right) \\ \phi=\tan ^{-1}\left(\frac{y}{x}\right)\end{array}\right.\right.$
The transformations between rectangular and cylindrical coordinate systems are :

$$
\begin{aligned}
& \left\{\begin{array} { c } 
{ x = \rho \operatorname { c o s } ( \phi ) } \\
{ y = \rho \operatorname { s i n } ( \phi ) } \\
{ z = z }
\end{array} \quad \& \quad \left\{\begin{array}{c}
\rho=\sqrt{x^{2}+y^{2}} \\
\phi=\tan ^{-1}\left(\frac{y}{x}\right) \\
z=z
\end{array}\right.\right. \\
& \vec{\nabla} f=\vec{e}_{1} \frac{1}{h_{1}} \frac{\partial f}{\partial u_{1}}+\vec{e}_{2} \frac{1}{h_{2}} \frac{\partial f}{\partial u_{2}}+\vec{e}_{3} \frac{1}{h_{3}} \frac{\partial f}{\partial u_{3}}
\end{aligned} \quad \begin{aligned}
& \vec{\nabla} \bullet \vec{F}=\frac{1}{h_{1} h_{2} h_{3}}\left(\frac{\partial\left(F_{1} h_{2} h_{3}\right)}{\partial u_{1}}+\frac{\partial\left(F_{2} h_{1} h_{3}\right)}{\partial u_{2}}+\frac{\partial\left(F_{3} h_{1} h_{2}\right)}{\partial u_{3}}\right) \\
& \vec{\nabla} \times \vec{F}=\frac{\vec{e}_{1}}{h_{2} h_{3}}\left(\frac{\partial\left(F_{3} h_{3}\right)}{\partial u_{2}}-\frac{\partial\left(F_{2} h_{2}\right)}{\partial u_{3}}\right)+\frac{\vec{e}_{2}}{h_{1} h_{3}}\left(\frac{\partial\left(F_{1} h_{1}\right)}{\partial u_{3}}-\frac{\partial\left(F_{3} h_{3}\right)}{\partial u_{1}}\right)+\frac{\vec{e}_{3}}{h_{1} h_{2}}\left(\frac{\partial\left(F_{2} h_{2}\right)}{\partial u_{1}}-\frac{\partial\left(F_{1} h_{1}\right)}{\partial u_{2}}\right)
\end{aligned}
$$

where $\vec{F}=\vec{e}_{1} F_{1}+\vec{e}_{2} F_{2}+\vec{e}_{3} F_{3} \quad$ and

| $\left(u_{1}, u_{2}, u_{3}\right)$ | represents | $(x, y, z)$ | for rectangular coordinate system |
| :---: | :---: | :--- | :--- |
|  | represents | $(\rho, \phi, z)$ | for cylindrical coordinate system |
|  | represents | $(r, \theta, \phi)$ | for spherical coordinate system |
| $\left(\vec{e}_{1}, \vec{e}_{2}, \vec{e}_{3}\right)$ | represents | $\left(\vec{e}_{x}, \vec{e}_{y}, \vec{e}_{z}\right)$ | for rectangular coordinate system |
|  | represents | $\left(\vec{e}_{\rho}, \vec{e}_{\phi}, \vec{e}_{z}\right)$ | for cylindrical coordinate system |
|  | represents | $\left(\vec{e}_{r}, \vec{e}_{\theta}, \vec{e}_{\phi}\right)$ | for spherical coordinate system |
| $\left(h_{1}, h_{2}, h_{3}\right)$ | represents | $(1,1,1)$ | for rectangular coordinate system |
|  | represents | $(1, \rho, 1)$ | for cylindrical coordinate system |
|  | represents | $(1, r, r \sin (\theta))$ | for spherical coordinate system |

$f(t)=f(t+2 L)=f(t+4 L)=\cdots=\sum_{n=0}^{\infty} a_{n} \cos \left(\frac{n \pi t}{L}\right)+\sum_{n=1}^{\infty} b_{n} \sin \left(\frac{n \pi t}{L}\right) \quad$ where
$a_{0}=\frac{1}{2 L} \int_{0}^{2 L} f(t) d t, a_{n}=\frac{1}{L} \int_{0}^{2 L} f(t) \cos \left(\frac{n \pi t}{L}\right) d t \& b_{0}=\frac{1}{L} \int_{0}^{2 L} f(t) \sin \left(\frac{n \pi t}{L}\right) d t$ for $n=1,2$
$\int(t \sin (k t)) d t=-\frac{t \cos (k t)}{k}+\frac{\sin (k t)}{k^{2}}$
$\int(t \cos (k t)) d t=\frac{t \sin (k t)}{k}+\frac{\cos (k t)}{k^{2}}$

