

UNIVERSITY OF SWAZILAND

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FACULTY OF SCIENCE

DEPARTMENT OF PHYSICS

SUPPLEMENTARY EXAMINATION 2016/2017

TITLE OF PAPER : MATHEMATICAL METHODS FOR  
PHYSICISTS

COURSE NUMBER : P272/PHY271

TIME ALLOWED : THREE HOURS

INSTRUCTIONS : ANSWER ANY FOUR OUT OF FIVE  
QUESTIONS.

EACH QUESTION CARRIES 25 MARKS.

MARKS FOR DIFFERENT SECTIONS ARE  
SHOWN IN THE RIGHT-HAND MARGIN.

THIS PAPER HAS EIGHT PAGES, INCLUDING THIS PAGE.

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**Question one**

Given  $\vec{F} = \vec{e}_\rho (4 \rho^3) + \vec{e}_\phi (2 \rho^3 \cos \phi) + \vec{e}_z (\rho z^2)$  in cylindrical coordinates,

(a) find the value of  $\oint_S \vec{F} \cdot d\vec{s}$  if  $S$  is the closed surface enclosing the cylindrical tube

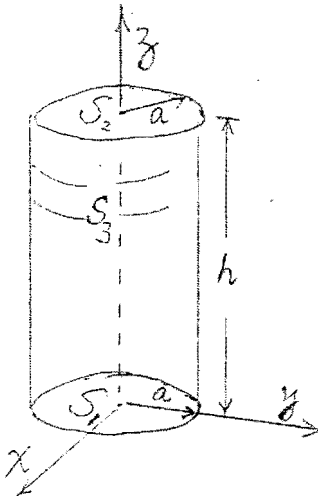
of cross-sectional radius  $a$  and tube height  $h$ , i.e.,  $S = S_1 + S_2 + S_3$  where

$$S_1 : (z = 0, 0 \leq \rho \leq a, 0 \leq \phi \leq 2\pi \text{ \& } d\vec{s} = -\vec{e}_z \rho d\rho d\phi)$$

$$S_2 : (z = h, 0 \leq \rho \leq a, 0 \leq \phi \leq 2\pi \text{ \& } d\vec{s} = +\vec{e}_z \rho d\rho d\phi)$$

$$S_3 : (\rho = a, 0 \leq \phi \leq 2\pi, 0 \leq z \leq h \text{ \& } d\vec{s} = \vec{e}_\rho \rho d\phi dz \xrightarrow{\rho=a} \vec{e}_\rho a d\phi dz)$$

The chosen closed surface  $S$  is shown in the diagram below :



**( 12 marks )**

(b) (i) find  $\vec{\nabla} \cdot \vec{F}$ ,

**( 4 marks )**

(ii) then evaluate the value of  $\iiint_V (\vec{\nabla} \cdot \vec{F}) dv$  where  $V$  is bounded by  $S$  given

in (a), i.e.,  $V : 0 \leq \rho \leq a, 0 \leq \phi \leq 2\pi, 0 \leq z \leq h$  &  $dv = \rho d\rho d\phi dz$ .

Compare this value with that obtained in (a) and make a brief comment.

**( 9 marks )**

Question two

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Given the following non-homogeneous differential equation as

$$\frac{d^2 x(t)}{dt^2} - \frac{dx(t)}{dt} - 2x(t) = 20e^{-3t} + 5\cos(2t) ,$$

- (a) set its particular solution as  $x_p(t) = k_1 e^{-3t} + k_2 \sin(2t) + k_3 \cos(2t)$  and find the values of  $k_1$  ,  $k_2$  &  $k_3$  . ( 10 marks )

- (b) for the homogeneous part of the given non-homogeneous differential equation , i.e.,

$$\frac{d^2 x(t)}{dt^2} - \frac{dx(t)}{dt} + 2x(t) = 0 , \text{ set } x(t) = e^{\alpha t} \text{ and find the appropriate values of } \alpha \text{ and}$$

thus write down its general solution  $x_h(t)$  ( 5 marks )

- (c) write down the general solution of the given non-homogeneous differential equation in terms of the answers obtained in (a) & (b) . If the initial conditions are

$$x(0) = 6 \quad \& \quad \left. \frac{dx(t)}{dt} \right|_{t=0} = -1 , \text{ find its specific solution } x_s(t) . \quad ( 10 \text{ marks } )$$

### Question three

Given the following Legendre's differential equation as :

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$$(1-x^2)\frac{d^2 y(x)}{dx^2} - 2x\frac{dy(x)}{dx} + 12y(x) = 0 \quad \dots\dots (1)$$

use the power series method , i.e., setting  $y(x) = \sum_{n=0}^{\infty} a_n x^{n+s}$  and  $a_0 \neq 0$  ,

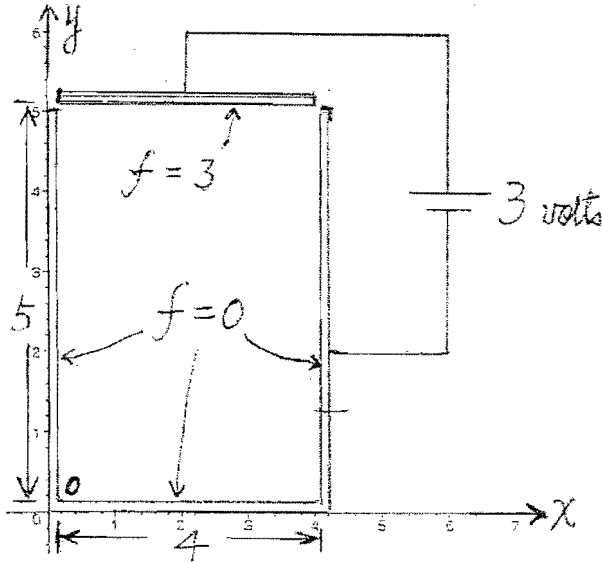
(a) write down the indicial equations. Find the values of  $s$  and  $a_1$  . Show that  $a_1$  can be zero resulting from the indicial equations and thus use  $a_1 = 0$  for the subsequent calculations in (b). **( 10 marks )**

(b) write down the recurrence relation. For all the appropriate values of  $s$  found in (a), set  $a_0 = 1$  and use the recurrence relation to calculate the values of  $a_n$  up to the value of  $a_6$  . Thus write down two independent solution in their power series forms and show that one of the solutions is a polynomial. **( 15 marks )**

Question four

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An U – tube capacitor extended very long into z direction with its x – y cross section of area  $4 \times 5$  as shown below :



Its electric potential  $f(x, y)$  for the space in-between the two conductors, i.e.,  $0 < x < 4$  &  $0 < y < 5$  , satisfies the following two dimensional Laplace equation :

$$\frac{\partial^2 f(x, y)}{\partial x^2} + \frac{\partial^2 f(x, y)}{\partial y^2} = 0 \quad \dots\dots (1)$$

If connecting 3 volts battery to the given capacitor, the boundary conditions for the capacitor are

$$f(0, y) = 0 \quad , \quad f(4, y) = 0 \quad , \quad f(x, 0) = 0 \quad \& \quad f(x, 5) = 3$$

(a) set  $f(x, y) = F(x) G(y)$  and use separation scheme to deduce the following ordinary differential equations :

$$\begin{cases} \frac{d^2 F(x)}{d x^2} = -k^2 F(x) \\ \frac{d^2 G(y)}{d y^2} = +k^2 G(y) \end{cases}$$

where  $k$  is a separation constant.

(5 marks)

**Question four (continued)**

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(b) write the general solution for (a) as

$$f(x, y) = \sum_{\forall k} f_k(x, y)$$

$$= \sum_{\forall k} (A_k \cos(kx) + B_k \sin(kx)) (C_k \cosh(ky) + D_k \sinh(ky))$$

where  $A_k$ ,  $B_k$ ,  $C_k$  &  $D_k$  are arbitrary constants.

Apply three zero boundary conditions which are equivalent to

$$f_k(0, y) = 0, f_k(4, y) = 0 \text{ \& } f_k(x, 0) = 0, \text{ and show that the general solution can be}$$

simplified as :

$$f(x, y) = \sum_{n=1}^{\infty} E_n \sin\left(\frac{n\pi x}{4}\right) \sinh\left(\frac{n\pi y}{4}\right)$$

where  $E_n$   $n=1, 2, 3, \dots$  are arbitrary constants.

**( 10 marks )**

(c) Apply the non-zero boundary condition, i.e.,  $f(x, 5) = 3$ , deduce that

$$E_n = \frac{6(1 - \cos(n\pi))}{n\pi \sinh\left(\frac{5n\pi}{4}\right)} \quad n=1, 2, 3, \dots$$

**( 10 marks )**

(Hint :  $\int_0^4 \sin\left(\frac{n\pi x}{4}\right) \sin\left(\frac{m\pi x}{4}\right) dx = 2 \delta_{n,m} = \begin{cases} 0 & \text{if } n \neq m \\ 2 & \text{if } n = m \end{cases}$  )

### Question five

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Given the following equations for coupled oscillator system as :

$$\begin{cases} \frac{d^2 x_1(t)}{dt^2} = -6 x_1(t) + 3 x_2(t) \\ \frac{d^2 x_2(t)}{dt^2} = 4 x_1(t) - 5 x_2(t) \end{cases}$$

(a) Set  $x_1(t) = X_1 e^{i\omega t}$  &  $x_2(t) = X_2 e^{i\omega t}$ , deduce the following matrix equation

$$A X = -\omega^2 X \quad \text{where} \quad A = \begin{pmatrix} -6 & 3 \\ 4 & -5 \end{pmatrix} \quad \& \quad X = \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \quad (4 \text{ marks})$$

(b) Find the eigenfrequencies  $\omega_1$  &  $\omega_2$  of the given coupled system. (6 marks)

(c) Find the eigenvectors  $\bar{X}_1$  &  $\bar{X}_2$  of the given coupled system corresponding to each eigenfrequencies  $\omega_1$  &  $\omega_2$  found in (b) respectively. (6 marks)

(d) Set  $x(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix}$ , then the general solution of  $x(t)$  in terms of the eigenfrequencies and eigenvectors found in (b) and (c) can be written as

$$x(t) = k_1 \cos(\omega_1 t) \bar{X}_1 + k_2 \sin(\omega_1 t) \bar{X}_1 + k_3 \cos(\omega_2 t) \bar{X}_2 + k_4 \sin(\omega_2 t) \bar{X}_2 \quad \text{where}$$

$k_1, k_2, k_3$  &  $k_4$  are arbitrary constants.

If the initial conditions of the system are given as :

$$x_1(0) = 2, \quad x_2(0) = 0, \quad \dot{x}_1(0) = -1 \quad \& \quad \dot{x}_2(0) = 0, \quad \text{then find the specific values of}$$

$k_1, k_2, k_3$  &  $k_4$  which satisfies the given initial conditions. (9 marks)

Useful informations

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The transformations between rectangular and spherical coordinate systems are :

$$\left\{ \begin{array}{l} x = r \sin(\theta) \cos(\phi) \\ y = r \sin(\theta) \sin(\phi) \\ z = r \cos(\theta) \end{array} \right. \quad \& \quad \left\{ \begin{array}{l} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1} \left( \frac{\sqrt{x^2 + y^2}}{z} \right) \\ \phi = \tan^{-1} \left( \frac{y}{x} \right) \end{array} \right.$$

The transformations between rectangular and cylindrical coordinate systems are :

$$\left\{ \begin{array}{l} x = \rho \cos(\phi) \\ y = \rho \sin(\phi) \\ z = z \end{array} \right. \quad \& \quad \left\{ \begin{array}{l} \rho = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1} \left( \frac{y}{x} \right) \\ z = z \end{array} \right.$$

$$\bar{\nabla} f = \bar{e}_1 \frac{1}{h_1} \frac{\partial f}{\partial u_1} + \bar{e}_2 \frac{1}{h_2} \frac{\partial f}{\partial u_2} + \bar{e}_3 \frac{1}{h_3} \frac{\partial f}{\partial u_3}$$

$$\bar{\nabla} \cdot \bar{F} = \frac{1}{h_1 h_2 h_3} \left( \frac{\partial(F_1 h_2 h_3)}{\partial u_1} + \frac{\partial(F_2 h_1 h_3)}{\partial u_2} + \frac{\partial(F_3 h_1 h_2)}{\partial u_3} \right)$$

$$\begin{aligned} \bar{\nabla} \times \bar{F} = & \frac{\bar{e}_1}{h_2 h_3} \left( \frac{\partial(F_3 h_3)}{\partial u_2} - \frac{\partial(F_2 h_2)}{\partial u_3} \right) + \frac{\bar{e}_2}{h_1 h_3} \left( \frac{\partial(F_1 h_1)}{\partial u_3} - \frac{\partial(F_3 h_3)}{\partial u_1} \right) \\ & + \frac{\bar{e}_3}{h_1 h_2} \left( \frac{\partial(F_2 h_2)}{\partial u_1} - \frac{\partial(F_1 h_1)}{\partial u_2} \right) \end{aligned}$$

where  $\bar{F} = \bar{e}_1 F_1 + \bar{e}_2 F_2 + \bar{e}_3 F_3$  and

$(u_1, u_2, u_3)$	represents	$(x, y, z)$	for rectangular coordinate system
	represents	$(\rho, \phi, z)$	for cylindrical coordinate system
	represents	$(r, \theta, \phi)$	for spherical coordinate system

$(\bar{e}_1, \bar{e}_2, \bar{e}_3)$	represents	$(\bar{e}_x, \bar{e}_y, \bar{e}_z)$	for rectangular coordinate system
	represents	$(\bar{e}_\rho, \bar{e}_\phi, \bar{e}_z)$	for cylindrical coordinate system
	represents	$(\bar{e}_r, \bar{e}_\theta, \bar{e}_\phi)$	for spherical coordinate system

$(h_1, h_2, h_3)$	represents	$(1, 1, 1)$	for rectangular coordinate system
	represents	$(1, \rho, 1)$	for cylindrical coordinate system
	represents	$(1, r, r \sin(\theta))$	for spherical coordinate system