

UNIVERSITY OF SWAZILAND

FACULTY OF SCIENCE

DEPARTMENT OF PHYSICS

SUPPLEMENTARY EXAMINATION 2017/2018

**TITLE OF PAPER : MATHEMATICAL METHODS FOR
PHYSICISTS**

COURSE NUMBER : P272/PHY271

TIME ALLOWED : THREE HOURS

**INSTRUCTIONS : ANSWER ANY FOUR OUT OF FIVE
QUESTIONS.**

EACH QUESTION CARRIES 25 MARKS.

**MARKS FOR DIFFERENT SECTIONS ARE
SHOWN IN THE RIGHT-HAND MARGIN.**

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P272/PHY271 MATHEMATICAL METHODS FOR PHYSICIST

Question one

- (a) Given the following relations between the unit vectors of cylindrical, spherical and Cartesian coordinate systems as

$$\begin{cases} \vec{e}_\rho = \vec{e}_x \cos(\phi) + \vec{e}_y \sin(\phi) \\ \vec{e}_\phi = -\vec{e}_x \sin(\phi) + \vec{e}_y \cos(\phi) \end{cases} \quad \& \quad \begin{cases} \vec{e}_r = \vec{e}_\rho \sin(\theta) + \vec{e}_z \cos(\theta) \\ \vec{e}_\theta = \vec{e}_\rho \cos(\theta) - \vec{e}_z \sin(\theta) \end{cases}$$

and deduce the following:

(i) $\frac{d\vec{e}_\phi}{dt} = -\vec{e}_\rho \frac{d\phi}{dt}$ in terms of cylindrical unit vectors ; **(3 marks)**

(ii) $\frac{d\vec{e}_\phi}{dt} = -\vec{e}_r \sin(\theta) \frac{d\theta}{dt} - \vec{e}_\theta \cos(\theta) \frac{d\theta}{dt}$ in terms of spherical unit vectors . **(4 marks)**

- (b) Given $\vec{F} = \vec{e}_x (3x^2 + yz) + \vec{e}_y (xz) + \vec{e}_z (xy)$ and find the value of

$$\int_{P_1, L}^{P_2} \vec{F} \cdot d\vec{l} \quad \text{if } P_1 : (0, 0, 2) , P_2 : (3, 9, 2) \quad \text{and}$$

- (i) L : a straight line from P_1 to P_2 on $z = 2$ plane , **(6 marks)**

- (ii) L : a cubic curved path $y = \frac{1}{3}x^3$ from P_1 to P_2 on $z = 2$ plane.

Compare this answer with that obtained in (b)(i) and comment on the conservative nature of the given vector field. **(7 + 1 marks)**

- (iii) Find $\vec{\nabla} \times \vec{F}$. Does this answer in agreement with the comment in (b)(ii) ? **(3 + 1 marks)**

Question two

Given a vector field $\vec{F} = \vec{e}_r (r^2 \cos(\theta)) + \vec{e}_\theta (2r^2) + \vec{e}_\phi (-3r^2 \cos(\phi))$ in spherical coordinates ,

(a) find the value of $\oint_S \vec{F} \cdot d\vec{s}$ if $S = S_1 + S_2$ where

$$S_1 : \left(r = 5, \frac{\pi}{2} \leq \theta \leq \pi, 0 \leq \phi \leq 2\pi \quad \& \quad d\vec{s} = \vec{e}_r r^2 \sin\theta d\theta d\phi \right)$$

$$\xrightarrow{r=5} \vec{e}_r 25 \sin\theta d\theta d\phi$$

$$S_2 : \left(\theta = \frac{\pi}{2}, 0 \leq r \leq 5, 0 \leq \phi \leq 2\pi \quad \& \quad d\vec{s} = -\vec{e}_\theta r \sin\theta dr d\phi \right)$$

$$\xrightarrow{\theta = \frac{\pi}{2}} -\vec{e}_\theta r dr d\phi$$

i.e., S is a lower-half semi-spherical closed surface centered at the origin with a radius of 5 . (10 marks)

(b) (i) Evaluate $\vec{\nabla} \cdot \vec{F}$ and show that

$$\vec{\nabla} \cdot \vec{F} = 4r \cos(\theta) + 2r \cot(\theta) + 3r \frac{\sin(\phi)}{\sin(\theta)} \quad . \quad (4 \text{ marks })$$

(ii) Find the value of $\iiint_V (\vec{\nabla} \cdot \vec{F}) dv$ where V is bounded by S given in (a), i.e.,

$$V : 0 \leq r \leq 5, \frac{\pi}{2} \leq \theta \leq \pi, 0 \leq \phi \leq 2\pi \quad \& \quad dv = r^2 \sin\theta dr d\theta d\phi .$$

Compare this answer to that obtained in (a) and make a brief comment.

(10+1 marks)

Question three

Given the following Bessel's differential equation as :

$$x^2 \frac{d^2 y(x)}{dx^2} + x \frac{dy(x)}{dx} + (x^2 - 4)y(x) = 0$$

Solve by using the power series method , i.e., setting $y(x) = \sum_{n=0}^{\infty} a_n x^{n+s}$ and $a_0 \neq 0$.

- (a) Write down the indicial equations. Deduce that $s = -2$ or $+2$ and $a_1 = 0$.

(9 marks)

- (b) Write down the recurrence relation. For $s = -2$ or $+2$, set $a_0 = 1$ and use the recurrence relation to calculate the values of a_n up to the value of a_6 . Thus write down two independent solution in their power series forms and show that one of the series solutions is a divergent series and the other is linearly dependent to the well-known Bessel's function

of the first kind of order 2 , i.e., $J_2(x) \left(\equiv \frac{1}{8} x^2 - \frac{1}{96} x^4 + \frac{1}{3072} x^6 - \frac{1}{184320} x^8 + \dots \right)$.

(12+4 marks)

Question four

An elastic string of length 9 is fixed at its two ends, i.e., at $x=0$ & $x=9$ and its transverse deflection $u(x,t)$ satisfies the following one-dimensional wave equation

$$\frac{\partial^2 u(x,t)}{\partial t^2} = 4 \frac{\partial^2 u(x,t)}{\partial x^2} .$$

- (a) Set $u(x,t) = F(x) G(t)$ and use separation scheme to deduce the following ordinary differential equations :

$$\begin{cases} \frac{d^2 F(x)}{dx^2} = k F(x) \\ \frac{d^2 G(t)}{dt^2} = 4 k G(t) \end{cases}$$

where k is a separation constant.

In view of the given boundary conditions, k should be a negative constant, i.e., $k < 0$, explain briefly why? (4+1 marks)

- (b) By direct substitution, show that $u(x,t) = \sum_{n=1}^{\infty} E_n \sin\left(\frac{n\pi x}{9}\right) \cos\left(\frac{2n\pi t}{9}\right)$

where E_n $n=1,2,3,\dots$ are arbitrary constants, satisfies two fixed end conditions,

i.e., $u(0,t) = 0 = u(9,t)$, as well as zero initial speed condition, i.e., $\left. \frac{\partial u(x,t)}{\partial t} \right|_{t=0} = 0$.

(7 marks)

- (c) Then find E_n in terms of n if the initial position of the string, i.e., $u(x,0)$, is given

$$\text{as } u(x,0) = \begin{cases} 2x & \text{if } 0 \leq x \leq 3 \\ -x+9 & \text{if } 3 \leq x \leq 9 \end{cases}$$

$$\text{(hint : } \int_{x=0}^9 \sin\left(\frac{n\pi x}{9}\right) \sin\left(\frac{m\pi x}{9}\right) dx = \begin{cases} 0 & \text{if } n \neq m \\ \frac{9}{2} & \text{if } n = m \end{cases} \quad \&$$

$$\int x \sin\left(\frac{n\pi x}{9}\right) dx = \frac{81}{n^2 \pi^2} \sin\left(\frac{n\pi x}{9}\right) - \frac{9}{n\pi} x \cos\left(\frac{n\pi x}{9}\right))$$

Thus calculate the values of E_1, E_2 and E_3 .

(10+3 marks)

Question five

Given the following non-homogeneous differential equation as

$$\frac{d^2 x(t)}{dt^2} + 6 \frac{dx(t)}{dt} + 13 x(t) = 10 e^{-4t} + 15 \sin(t) ,$$

- (a) find its particular solution $x_p(t)$ and show that

$$x_p(t) = 2 e^{-4t} + \sin(t) - \frac{1}{2} \cos(t) . \quad (9 \text{ marks})$$

- (b) Find the general solution $x_h(t)$ for the homogeneous part of the given differential

$$\text{equation, i.e., } \frac{d^2 x(t)}{dt^2} + 6 \frac{dx(t)}{dt} + 13 x(t) = 0 . \quad (6 \text{ marks})$$

- (c) Write down the general solution of the given non-homogeneous differential equation

$$x_g(t). \text{ If the initial conditions are given as } x(0) = -3 \text{ \& } \left. \frac{dx(t)}{dt} \right|_{t=0} = 5 , \text{ find its}$$

$$\text{specific solution } x_s(t) . \quad (1+9 \text{ marks})$$

Useful informations

The transformations between rectangular and spherical coordinate systems are :

$$\left\{ \begin{array}{l} x = r \sin(\theta) \cos(\phi) \\ y = r \sin(\theta) \sin(\phi) \\ z = r \cos(\theta) \end{array} \right. \quad \& \quad \left\{ \begin{array}{l} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1} \left(\frac{\sqrt{x^2 + y^2}}{z} \right) \\ \phi = \tan^{-1} \left(\frac{y}{x} \right) \end{array} \right.$$

The transformations between rectangular and cylindrical coordinate systems are :

$$\left\{ \begin{array}{l} x = \rho \cos(\phi) \\ y = \rho \sin(\phi) \\ z = z \end{array} \right. \quad \& \quad \left\{ \begin{array}{l} \rho = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1} \left(\frac{y}{x} \right) \\ z = z \end{array} \right.$$

$$\bar{\nabla} f = \bar{e}_1 \frac{1}{h_1} \frac{\partial f}{\partial u_1} + \bar{e}_2 \frac{1}{h_2} \frac{\partial f}{\partial u_2} + \bar{e}_3 \frac{1}{h_3} \frac{\partial f}{\partial u_3}$$

$$\bar{\nabla} \cdot \bar{F} = \frac{1}{h_1 h_2 h_3} \left(\frac{\partial(F_1 h_2 h_3)}{\partial u_1} + \frac{\partial(F_2 h_1 h_3)}{\partial u_2} + \frac{\partial(F_3 h_1 h_2)}{\partial u_3} \right)$$

$$\begin{aligned} \bar{\nabla} \times \bar{F} = & \frac{\bar{e}_1}{h_2 h_3} \left(\frac{\partial(F_3 h_3)}{\partial u_2} - \frac{\partial(F_2 h_2)}{\partial u_3} \right) + \frac{\bar{e}_2}{h_1 h_3} \left(\frac{\partial(F_1 h_1)}{\partial u_3} - \frac{\partial(F_3 h_3)}{\partial u_1} \right) \\ & + \frac{\bar{e}_3}{h_1 h_2} \left(\frac{\partial(F_2 h_2)}{\partial u_1} - \frac{\partial(F_1 h_1)}{\partial u_2} \right) \end{aligned}$$

where $\bar{F} = \bar{e}_1 F_1 + \bar{e}_2 F_2 + \bar{e}_3 F_3$ and

(u_1, u_2, u_3)	represents	(x, y, z)	for rectangular coordinate system
	represents	(ρ, ϕ, z)	for cylindrical coordinate system
	represents	(r, θ, ϕ)	for spherical coordinate system

$(\bar{e}_1, \bar{e}_2, \bar{e}_3)$	represents	$(\bar{e}_x, \bar{e}_y, \bar{e}_z)$	for rectangular coordinate system
	represents	$(\bar{e}_\rho, \bar{e}_\phi, \bar{e}_z)$	for cylindrical coordinate system
	represents	$(\bar{e}_r, \bar{e}_\theta, \bar{e}_\phi)$	for spherical coordinate system

(h_1, h_2, h_3)	represents	$(1, 1, 1)$	for rectangular coordinate system
	represents	$(1, \rho, 1)$	for cylindrical coordinate system
	represents	$(1, r, r \sin(\theta))$	for spherical coordinate system